Monolithic Digital IC 3-phase Sensor Less Motor Driver

Overview

The LB11685AV is a three-phase full-wave current-linear-drive motor driver IC. It adopts a sensor less control system without the use of a Hall Effect device. For quieter operation, the LB11685AV features a current soft switching circuit and be optimal for driving the cooling fan motors used in refrigerators, etc.

Functions

- Three-phase Full-wave Linear Drive (Hall Sensor-less Method)
- Built-in Current Limiter Circuit
- Built-in Three-phase Output Voltage Control Circuit
- Built-in Motor Lock Protection Circuit
- Motor Lock Protection Detection Output
- FG Output Made by Back EMF
- Built-in Thermal Shut Down Circuit
- Beat Lock Prevention Circuit

Specifications

MAXIMUM RATINGS ($T_A = 25^{\circ}C$)

| Parameter | Symbol | Conditions | Ratings | Unit |
|--------------------------------|--------------------------------|--------------------------------|-------------------------------|------|
| Maximum Supply Voltage | V _{CC} max | | 19 | V |
| Input Applied Voltage | V _{IN} max | | –0.3 to V _{CC} + 0.3 | V |
| Maximum Output Current | I _O max (Note 1) | | 1.2 | A |
| Allowable Power Dissipation | P _d max | Mounted on a board (Note 2) | 1.05 | W |
| Operating Temperature | T _{opr} | | -40 to +85 | °C |
| Storage Temperature | T _{stg} | | -55 to +150 | °C |
| Junction Temperature | T _j max | | 150 | °C |

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

1. The I_O is a peak value of motor-current.

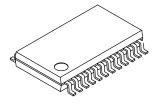
2. Specified board: 76.1 mm \times 114.3 mm \times 1.6 mm, glass epoxy board.

- **CAUTION:** Absolute maximum ratings represent the value which cannot be exceeded for any length of time.
- **CAUTION:** Even when the device is used within the range of absolute maximum ratings, as a result of continuous usage under high temperature, high current, high voltage, or drastic temperature change, the reliability of the IC may be degraded. Please contact us for the further details.



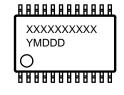
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SSOP24J CASE 565AS

MARKING DIAGRAM



XXXXX = Specific Device Code Y = Year M = Month DDD = Additional Traceability Data

PIN ASSIGNMENT

| UOUT (NC) PGND MCOM (NC) SGND FG RD (NC) V _{CO} CX | 1 2 3 4 5 6 7 8 9 10 11 12 | |) | | | 24 23 22 21 20 19 18 17 16 15 14 13 | VOUT WOUT (NC) (NC) RF V _{CC} REG VOH FC1 FC2 C2 C1 |
|---|---|--|---|--|--|--|---|
|---|---|--|---|--|--|--|---|

ORDERING INFORMATION

See detailed ordering and shipping information on page 7 of this data sheet.

RECOMMENDED OPERATING CONDITIONS (T_A = 25°C)

| Symbol | Parameter | Conditions | Ratings | Unit |
|--------------------|----------------------------|------------|-------------|------|
| V _{CC} | Recommended Supply Voltage | | 12.0 | V |
| V _{CC} op | Operating Supply Voltage | | 4.5 to 18.0 | V |

Functional operation above the stresses listed in the Recommended Operating Ranges is not implied. Extended exposure to stresses beyond the Recommended Operating Ranges limits may affect device reliability.

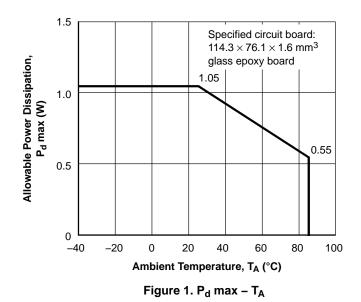
ELECTRICAL CHARACTERISTICS (T_C = 25°C unless otherwise noted)

| Symbol | Parameter | Conditions | Min | Тур 10 | Max 20 | Unit mA |
|----------------------|---|--|-------|------------------|---------------------|------------|
| I _{CC} | Supply Current | FC1 = FC2 = 0 V | 5 | | | |
| VREG | Internal Regulate Voltage | | 3.0 | 3.3 | 3.6 | V |
| VOSOUR | Output Voltage (Source) | I _O = 0.8 A (Note 5) | | 1.3 | 1.7 | V |
| VOSINK | Output Voltage (Sink) | I _O = 0.8 A (Note 5) | | 0.5 | 1.3 | V |
| VOLIM | Current Limiter | | 0.268 | 0.300 | 0.332 | V |
| VINCOM | MCOM Pin Common-input Voltage Range | | 0 | | V _{CC} – 2 | V |
| ICOM+ | MCOM Pin Source Current for Hysteresis | MCOM = 7 V | 30 | | 80 | μΑ |
| ICOM- | MCOM Pin Sink Current for Hysteresis | MCOM = 7 V | 30 | | 80 | μΑ |
| RTCOM | MCOM Pin Hysteresis Current Ratio | RTCOM = ICOM+ / ICOM- | 0.6 | | 1.4 | |
| I _{VCO} | VCO Input Bias Current | V _{CO} = 2.3 V | | | 0.2 | μΑ |
| $f_{VCO}min$ | VCO Oscillation Minimum Frequency | V_{CO} = 2.1 V, CX = 0.015 μ F Design target (Note 4) | | 930 | | Hz |
| f _{VCO} max | VCO Oscillation Maximum Frequency | V_{CO} = 2.7 V, CX = 0.015 μ F Design target (Note 4) | | 8.6 | | kHz |
| I _{CX} | CX Charge/Discharge Current | V _{CO} = 2.5 V, CX = 1.6 V | 70 | 100 | 140 | μΑ |
| ΔVCX | CX Hysteresis Voltage | | 0.35 | 0.55 | 0.75 | |
| IC1(2)+ | C1 (C2) Charge Current | V _{CO} = 2.5 V, C1(2) = 1.3 V | 12 | 20 | 28 | μΑ |
| IC1(2)- | C1 (C2) Discharge Current | V _{CO} = 2.5 V, C1(2) = 1.3 V | 12 | 20 | 28 | μA |
| RTC1(2) | C1 (C2) Charge/Discharge Current Ratio | RTC1(2) = IC1(2)+ / IC1(2)- | 0.8 | 1.0 | 1.2 | |
| RTCCHG | C1/C2 Charge Current Ratio | RTCCHG = IC1+ / IC2+ | 0.8 | 1.0 | 1.2 | |
| RTCDIS | C1/C2 Discharge Current Ratio | RTCDIS = IC1- / IC2- | 0.8 | 1.0 | 1.2 | |
| VCW1(2) | C1 (C2) Cramp Voltage Width | | 1.0 | 1.3 | 1.6 | V |
| VFGL | FG Output Low Level Voltage | IFG = 3 mA | | | 0.5 | V |
| VRDL | RD Output Low Level Voltage | IRD = 3 mA | | | 0.5 | V |
| TTSD | Thermal Shut Down Operating Temperature (Note 3) | Junction temperature Design target (Note 4) | 150 | 180 | | °C |
| ∆TTSD | Thermal Shut Down Hysteresis Temperature (Note 3) | Junction temperature Design target (Note 4) | | 15 | | °C |

Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions. 3. The thermal shut down circuit is built-in for protection from damage of IC. But its operation is out of T_{opr}. Design thermal calculation at normal

operation.

4. Design target value and no measurement is made. 5. The I_O is a peak value of motor-current.



BLOCK DIAGRAM

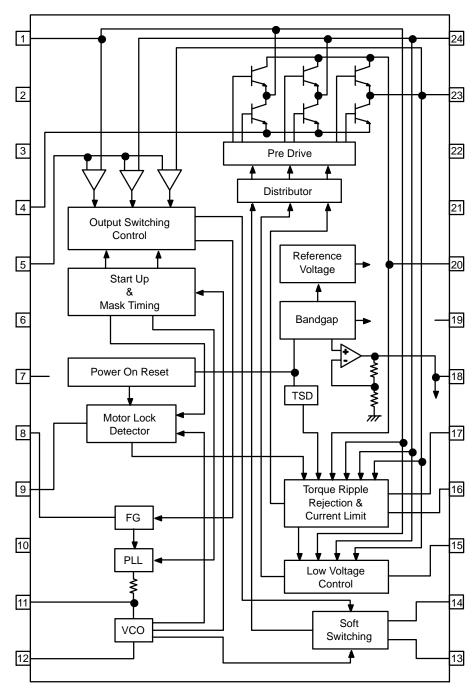


Figure 2. Block Diagram

PIN FUNCTION

PIN FUNCTION

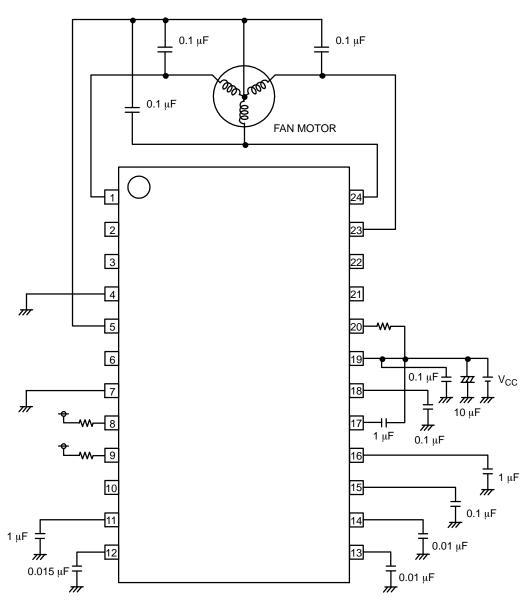
| Pin No. | Pin Name | Function | Equivalent Circuit |
|---------------|----------------------|---|--|
| 1 23 24 | UOUT WOUT VOUT | Each output pin of three phases. | Pin No. 20 |
| 4 | PGND | GND pin in the output part. This pin is connected to GND. The SGND pin is also connected to GND | Pin No. 1, 23, 24 |
| 20 | RF | Pin to detect output current. By connecting a resistor between this pin and V_{CC} , the output current is detected as a voltage. The current limiter is operated by this voltage. | Pin No. 4 |
| 5 | мсом | Motor coil midpoint input pin. The coil voltage waveform is detected based on this voltage. | Pin No. 5 |
| 7 | SGND | Ground pin (except the output part) This pin is connected to GND. The PGND pin is also connected to GND. | |
| 8 | FG | FG out made by back EMF pin. It synchronizes FG out with inverted V-phase. When don't use this function, open this pin. | Pin No. 8, 9 |
| 9 | RD | Motor lock protection detection output pin. Output with L during rotation of motor. Open during lock protection of motor (High-impedance). When don't use this function, open this pin. | SGND ↓ SGND |
| 11 | VCO | PLL output pin and VCO input pin. To stabilize PLL output, connect a capacitor between this pin and GND. | VREG Vcc Vcc VREG Vcc VREG SGND VREG SGND VREG VREG VREG VREG VREG VREG VREG |

PIN FUNCTION (continued)

| Pin No. | Pin Name | Function | Equivalent Circuit |
|----------|----------|--|---|
| 12 | СХ | VCO oscillation output pin. Operation frequency range and minimum frequency are determined by the capacity of the capacitor connected to this pin. | VREG Vcc Pin No. 12 SGND SGND |
| 13 14 | C1 C2 | Soft switching adjustment pin. The triangular wave from is form formed by connecting a capacitor with this pin. And, the switching of three-phase output is adjusted by the slope. | Pin No. 13, 14 |
| 15 | FC2 | Frequency characteristic correction pin 2. To suppress the oscillation of control system closed loop of sink-side, connect a capacitor between this pin and GND. | VREG Vcc Pin No. 15 SGND SGND |
| 16 | FC1 | Frequency characteristic correction pin 1. To suppress the oscillation of control system closed loop of source-side, connect a capacitor between this pin and GND. | Pin No. 16 |
| 17 | VOH | Three-phase output high level output pin. To stabilize the output voltage of this pin, connect a capacitor between this pin and the V_{CC} pin. | Pin No. 17 |
| 18 | VREG | DC voltage (3.3 V) output pin. Connect a capacitor between this pin and GND for stabilization. | Pin No. 18 |
| 19 | VCC | Pin to supply power-supply voltage. To curb the influence of ripple and noise. The voltage should be stabilized. | |

APPLICATION CIRCUIT EXAMPLE

* Each fixed number in the following Figure 3, is the referential value.





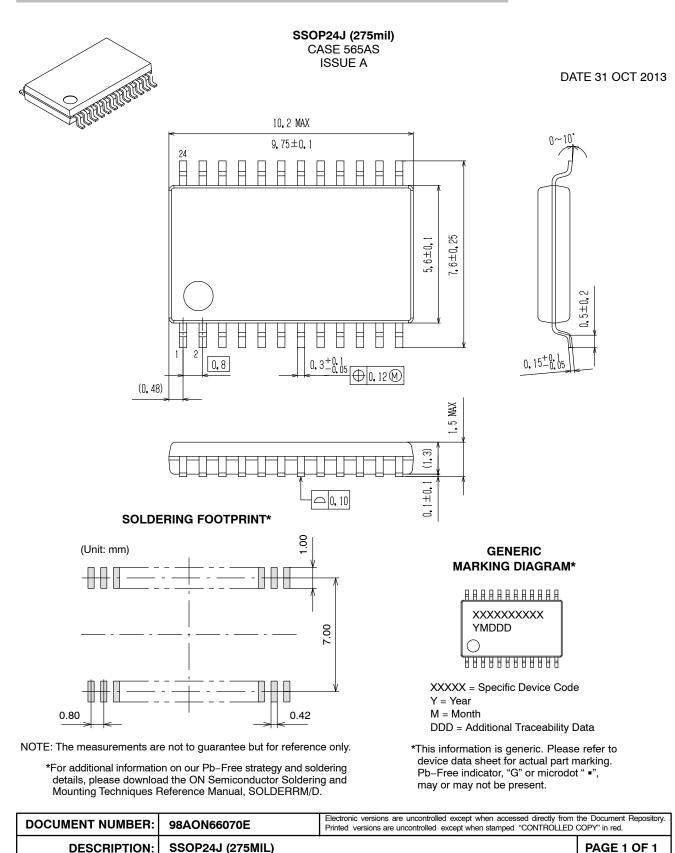
ORDERING INFORMATION

| Device | Package | Wire Bond | Shipping [†] (Qty / Packing) |
|-----------------|--|-----------|---------------------------------------|
| LB11685AV-TLM-H | SSOP24J (275mil) (Pb-Free / Halogen Free) | Au-wire | 2000 / Tape & Reel |
| LB11685AV-W-AH | SSOP24J (275mil) (Pb-Free / Halogen Free) | Cu-wire | 2000 / Tape & Reel |

+For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, <u>BRD8011/D</u>.







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